Automation System TROVIS 5400 Repeater TROVIS 5482





Mounting and operating instructions



EB 5409-1 EN

Edition December 2000

CE

Contents

Application	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	2
Principle of operation	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	3
Opening the device .	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	4
Electrical connections	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	6
Installation	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	•	8
Technical data																								•		•								8

1 Application

The TROVIS 5482 Repeater is used in a RS-485 bus system to increase the line length by 1200 m.

It can also be used to convert data for a 4-wire bus system into data for a 2-wire bus system.



Assembly, start-up and operation of the device may only be performed by trained and experienced personnel familiar with this product.

2 Principle of operation

The device is equipped with two interfaces, X1 and X2, which are electrically isolated from each other as well as from the PE connection.

Four LEDs are located on the front side of the device. When they are illuminated or blink, the following conditions are signalled:

- Power on
- ⊖ X1 sending data
- X1 receiving data
- X2 recognizes that transmitter is active (DCD)

There is a series of jumpers on the printed circuit board inside the device which allows the repeater to be adapted to the requirements of a RS-485 bus system. Fig. 1 illustrates the position of the jumpers. The casing can be opened as described in section 3. The following functions can be selected or set (for the exact jumper settings and the default positions refer to Tables 1 to 6):

Selecting a 2-wire or 4-wire system

Depending on the bus system used, a 2-wire or 4-wire system must be selected for each interface (see Table 1).

Bus termination of interfaces

The bus can be terminated both at interface X1 and at X2 by positioning the jumpers X6, X7 and X11, X12 as shown in Table 2.

Controlling the transmitter for interface X2

A signal level detector is located at both interfaces. It recognizes whenever a bus station sends data (transmitter activated). In the 2-wire system, it controls the switching between sending and receiving data. The signal level detector can be disabled. In that case, sending and receiving are switched over by the data itself (see Table 3). An adjustment of the transmission rate is not necessary.

Blocking duration of the transmitter

In the 2-wire system, one interface is blocked whenever the other interface sends data. Jumpers X16 and X17 allow the duration of the blocking to be changed, should communication problems occur (see Table 4).

Increasing the duration of the transmitter's switching signal for X2

In order to prevent reflections in the lines of the 2-wire system, the transmitter's switching signal can be lengthened. This is only possible for the interface X2 (see Table 5).

Grounding the interfaces

If necessary for older devices, it is possible to ground the interfaces X1 or X2 by changing the position of the jumper X5 as described in Table 6.

3 Opening the device

Do not open the device, unless the power is turned off. The device may only be opened by experienced personnel!

When changing the jumper positions according to the instructions in section 2, proceed as follows:

- 1. Disconnect mains plug, if necessary.
- 2. Loosen the two screws located on the bottom of the case.
- 3. Separate the two case parts, taking care that the front panel does not fall out.
- 4. Remove the front panel and set aside.
- 5. Change the jumper positions according to Tables 1 to 6.
- 6. Replace the front panel, making sure the holes and LEDs are properly aligned with one another.
- 7. Reassemble the two case parts and screw back together using the two screws.



Table 1 · Selecting a 2-wire system or 4-wire system							
Interface	Circuit	Jumper					
		Designation	Position				
×1	2-wire		1-2				
XI	4-wire	X8, X9, X10	2-3				
VO	2-wire	X13, X14,	1-2				
X2	4-wire	X15	2-3				

Table 2 · Bus termination of interfaces							
Interface	Bus ter-	Jumper					
	mination	Designation	Position				
¥1	Yes		1-2				
X1	No	X6, X/	2-3				
NO.	Yes		1-2				
X2	No	XII, XI2	2-3				

Table 4 · Blocking duration of a transmitter								
Interface	Time in μs	Jumper						
		Designation	Position					
	40 ±20 %		1-2					
X1	80 ± 20%	X16	3-4					
	120 ± 20%		5-6					
	40 ± 20%		1-2					
X2	80 ± 20%	X17	3-4					
	120 ± 20%		5-6					

Table 5 · Increasing	duration	of transmitter's
switching signal for	X2	

Function	Jumper				
	Designation	Position			
Not delayed (3 µs)		1-2			
0.75 ms ± 20%	X19	3-4			
$1.5 \text{ ms} \pm 20\%$		5-6			

Table 6 · Grounding the interfaces						
Function	Jumper					
	Designation	Position				
X1 grounded		1-2				
Electrically isolated interfaces	X5	2-3				
X2 grounded		3-4				

Table 3 · Controlling the transmitter for interface X2							
Function	Jumper						
	Designation	Position					
By data		1-2					
By signal level detector	X18	2-3					

Default setting



4 Electrical connections

The power supply connection 230 V as well as both terminals for the interfaces X1 and X2 are located on the rear panel as shown in Fig. 2.

Connect the data lines for interfaces X1 and X2 to the supplied 5-pin connectors using screw terminals. For the data lines, we recommend using a twisted pair of wires, non-screened cable with a cross-section of 0.5 mm^2 , a cable capacitance of maximum 100 nF/km and a line resistance of maximum 100 nF/km. Use a shielded cable if the electrical interference is strong. The shielding must only be connected at one end to prevent ground currents. It must be noted that the transmission properties are reduced with increased cable capacitance and smaller cable cross-sections which leads to a reduction in the bus range.

For the assignment of the data line connections, depending on the type of line selected, refer to Tables 7 and 8. Fig. 3 shows the typical wiring in a 4-wire system.

Use the power supply cable supplied for the power supply connection 230 V.

Table 7 · 2-wire terminal for X1 and X2							
	Terminal	Designation					
1	Input/Output	В					
2	Input/Output	А					
3	Not assigned						
4	Not assigned						
5	Shield						

Table 8 · 4-wire terminal for X1 and X2						
	Terminal	Designation				
1	Input	$R_B (R_{x+})$				
2	Input	R _A (Rx-)				
3	Output	T _B (T _{x+})				
4	Output	T _A (T _{x-})				
5	Shield					



5 Installation

The device can either be placed on an uneven surface using the 4 rubber pads supplied or fixed with two Velcro strips.

Rubber pads

Remove the protective backing! Stick the rubber pads onto the underside of the device.

Velcro strips

Two pairs of Velcro strips are supplied with the device. The Velcro strips also have a

self-adhesive side and can be fixed as follows :

- 1. First remove the protective backing from one side of the strip!
- 2. Stick strips on the left and right side of the top or bottom of the device!
- 3. Remove the protective backing from the other side of the strip!
- 4. Stick the device with the Velcro strips onto the desired location!

Device	TROVIS 5482	S
Data transmission	Asynchronous, full-/half-du- plex or simplex	P
Interface 1	RS 485 or RS 422 A 2- or 4-wire transmission	S P
Interface 2	RS 485 or RS 422 A 2- or 4-wire transmission via 5-pin connector	
Transmission rate	0 to 100000 Bit/s; code transparent	
Running time of device	For 4-wire systems: appr. 0,2 μs independent of transmission rate For 2-wire systems and for conversion between 2- and 4-wire systems: minimum 45 μs	te H C
Indicators	4 LEDs for power, TD, RD and status	V
Isolation	Electrical isolation of data li- nes using optocouplers; Supply isolation through transformer, PE conductor used to discharge interfe- rence current	

420 V effective upply isolation 230 VAC, 50/60 Hz, otower supply hers available on request 1.8 m; separate upply cable Maximum 3.5 VA ower onsumption loise immunity According to EN 50082 Part 2 According to EN 50081 loise emission Part 1 mbient 5 to 50 °C emperature 0 to 95 % relative air lumiditv humidity Plastic ABS, black; rear pa-Case material nel: aluminum stallation With rubber pads or Velcro strips Veight 0.4 kg 129 x 47 x 134 imensions



6 Technical data